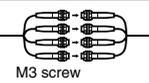
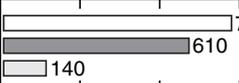
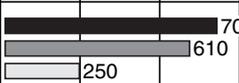
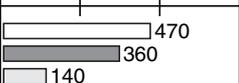
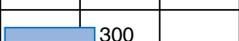
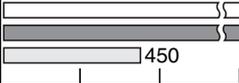
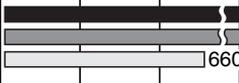
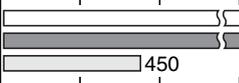
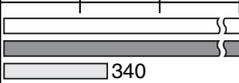
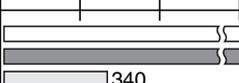


Area sensing  
Throughbeam fiber units

High resolution mode  
 Super long-distance mode  
 Green light  
 Standard mode  
 Super high-speed mode  
 Red light

Features	Appearance	Applicable Amplifier Unit	Sensing distance (mm) <sup>*1</sup> (Parentheses: With E39-F1 Lens Unit)	Standard object <sup>*2</sup> (min. sensing object) (Parentheses: Opaque object)	Model	Permissible bending radius	
Multi-point detection (4-head)	 <p>M3 screw</p>	E3X-DA□-S		2 mm ø (0.1 mm ø)	E32-M21	25 mm	
		E3X-DA□-N		2.0 mm ø (0.01 mm ø)			
		E3X-MDA		2 mm ø (0.1 mm ø)			
		E3X-NA□(V)		2.0 mm ø (0.03 mm ø)			
		E3X-NA□F		2.0 mm ø (0.3 mm ø)			
Detects in a 30 mm area Free-cut	 <p>30 mm</p>	E3X-DA□-S		(0.3 mm ø) <sup>*4</sup>	E32-T16W	10 mm	
		E3X-DA□-N					
		E3X-MDA					
		E3X-NA□(V)		(0.5 mm ø) <sup>*3</sup>			
		E3X-NAG□					
		E3X-NA□F		(4.0 mm ø) <sup>*3</sup>			
		E3X-DA□-S			(0.3 mm ø) <sup>*4</sup>	E32-T16WR	1 mm
		E3X-DA□-N					
		E3X-MDA					
		E3X-NA□(V)		(0.5 mm ø) <sup>*3</sup>			
		E3X-NA□F		(4.0 mm ø) <sup>*3</sup>			

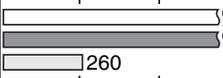
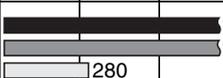
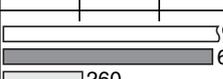
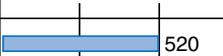
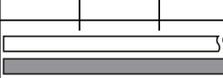
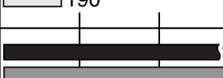
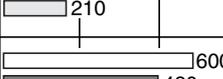
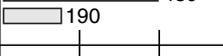
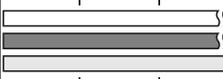
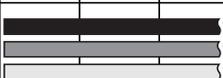
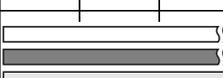
\*1. Sensing distance based on white paper.

\*2. Indicates values for standard mode.

\*3. The sensing distance is 100 mm, possible detection within specified area under static condition

\*4. The sensing distance is 300 mm, possible detection within specified area under static condition.

High resolution mode      Standard mode  
 Super long-distance mode      Super high-speed mode  
 Green light      Red light

Features	Appearance	Applicable Amplifier Unit	Sensing distance (mm) <sup>*1</sup> (Parentheses: With E39-F1 Lens Unit)	Standard object <sup>*2</sup> (min. sensing object) (Parentheses: Opaque object)	Model	Permissible bending radius		
Side-view suitable for applications with limited spatial depth Free-cut		E3X-DA□-S		(0.2 mm ø) <sup>*4</sup>	E32-T16J	10 mm		
		E3X-DA□-N						
		E3X-MDA						
		E3X-NA□(V)		(0.3 mm ø) <sup>*3</sup>				
		E3X-NAG□						
		E3X-NA□F		(2.0 mm ø) <sup>*3</sup>				
		E3X-DA□-S		(0.2 mm ø) <sup>*4</sup>			E32-T16JR	1 mm
		E3X-DA□-N						
		E3X-MDA						
		E3X-NA□(V)		(0.3 mm ø) <sup>*3</sup>				
E3X-NA□F		(2.0 mm ø) <sup>*3</sup>						
Suitable for detecting over a 10 mm area; long distance Free-cut		E3X-DA□-S		(0.6 mm ø) <sup>*5</sup>	E32-T16	25 mm		
		E3X-DA□-N						
		E3X-MDA						
		E3X-NA□(V)		(0.9 mm ø) <sup>*3</sup>				
		E3X-NAG□						
		E3X-NA□F		(1.5 mm ø) <sup>*3</sup>				

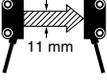
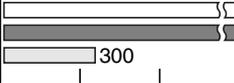
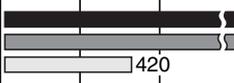
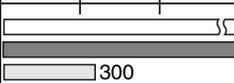
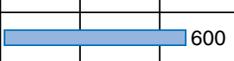
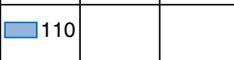
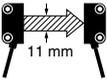
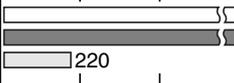
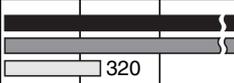
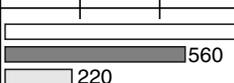
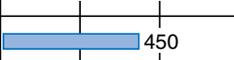
\*1. Sensing distance based on white paper.

\*2. Indicates values for standard mode.

\*3. The sensing distance is 100 mm, possible detection within specified area under static condition

\*4. The sensing distance is 300 mm, possible detection within specified area under static condition.

High resolution mode       Standard mode  
 Super long-distance mode       Super high-speed mode  
 Green light       Red light

Features	Appearance	Applicable Amplifier Unit	Sensing distance (mm) <sup>*1</sup> (Parentheses: With E39-F1 Lens Unit)	Standard object <sup>*2</sup> (min. sensing object) (Parentheses: Opaque object)	Model	Permissible bending radius
Stable for detecting minute sensing objects in a wide area Free-cut		E3X-DA□-S		(0.2 mm ø) <sup>*4</sup>	E32-T16P	10 mm
		E3X-DA□-N				
		E3X-MDA				
		E3X-NA□(V)		(0.3 mm ø) <sup>*3</sup>		
		E3X-NAG□				
		E3X-NA□F		(2.0 mm ø) <sup>*3</sup>		
Stable detection of minute sensing objects, wide sensing area Free-cut		E3X-DA□-S		(0.2 mm ø) <sup>*4</sup>	E32-T16PR	1 mm
		E3X-DA□-N				
		E3X-MDA				
		E3X-NA□(V)		(0.3 mm ø) <sup>*3</sup>		
		E3X-NA□F		(2.0 mm ø) <sup>*3</sup>		

\*1. Sensing distance based on white paper.

\*2. Indicates values for standard mode.

\*3. The sensing distance is 100 mm, possible detection within specified area under static condition

\*4. The sensing distance is 300 mm, possible detection within specified area under static condition.